

# Overlock Machine for Cotton Work Gloves

## UK2000H-WG

### MAIN SPECIFICATION

* Needle Size	DC x 27 ( No. 14 ~ 18 ), No. 18 is equipped with machine head.
* Needle Q'ty	1 piece
* Thread Q'ty	3 pcs. ( 4 pcs. ), Upper Looper : 2 pcs. of the thread
* Overedge Width	4 mm
* Stitch Length	Min. 0.5 mm ~ Max. 3.0 mm
* Feed Dog Type	1 piece feeding
* Presser Foot Lift	8 mm
* Machine Speed	Standard : 4,000 SPM. Max. 4,500 SPM
* Motor Pulley Size	80 mm
* Lubrication	Automatic Lubrication System

# Overlock Machine for Cotton Work Gloves

## UK2000H-WG

### INSTRUCTION MANUAL

#### 1. Needle Height

It is at 11 mm.

Adjustment is the same way of standard UK model.

#### 2. Distance between Lower Looper and Needle

It is at 3.3 ~ 3.5 mm, when lower looper is at the left dead point.

Adjustment is the same way of standard UK model.

#### 3. Distance between Upper Looper and Needle

It is at 4.0 ~ 4.5 mm, when upper looper is at the left dead point.

Adjustment is the same way of standard UK model.

#### 4. Feed Dog Height

It is at 1 mm, when the feed dog is at the highest position.

Adjustment is :

- 1) Please see Parts List 30. SPECIAL PARTS (8) UK2000H-WG (page 59 & 60)
- 2) Loosen the screw Ref No. 30-40 ( Part No. 54-126 ).
- 3) Then, adjust it .

#### 5. Feed Dog Tilting

It must be Horizontal and Parallel position against needle plate, when the feed dog is positioned above the needle plate.

Adjustment is :

- 1) Please see Parts List 30. SPECIAL PARTS (8) UK2000H-WG (page 59 & 60)
- 2) Loosen the screw Ref No. 30-45 ( Part No. 54-140 ).
- 3) Rotate the washer Ref No. 30-33 ( Part No. 56-660 ).
- 4) Then, adjust it.

#### 6. Stitch Length

Adjustment is :

- 1) Please see Parts List 30. SPECIAL PARTS (8) UK2000H-WG (page 59 & 60)
- 2) Loosen the nut Ref No. 30-46 ( Part No. 54-160 ).
- 3) Moving the pin Ref No. 30-15 ( Part No. 56-510 ).  
Moving the pin UPWARD : SMALL stitch length.  
Moving the pin DOWNWARD : BIG stitch length.
- 4) Then, adjust it.

Other Adjustment are the same way of standard UK model.